# Roller AC Servo System HMI-14 User Manual



## Safely Instruction

- Please read this manual carefully, also with related manual for the machinery before use the controller.
- For installing and operating the controller properly and safely, qualified engineers are required.
- Please stay away from arc welding equipment, in order to avoid electromagnetic interference and malfunction of the controller.
- Keep room temperature bellow 45°c and above 0°c
- Do not use in humidity below 30% or above 95% or dew and mist places.
- Please turn off the power and unplug the power cord, before install the control box and other components,
- To prevent interference or electric leakage accidents, please make the ground work; the power cord ground wire must be securely connected to earth by an effective way.
- All parts for the repair provided by the Company or approved before use.
- Please turn off the power and unplug the power cord before any maintenance action. There is dangerous high voltage control box, you must turn the power off after one minute before opening the control box.
- The symbol  $\triangle$  in this manual means Safety Precautions, please pay attention to it and strictly follow it, to avoid any unnecessary damage.

# 1 Installation Instructions

### 1.1 Product specifications

Product Type	ASE59	Supply Voltage	AC 220 ± 44 V
Power frequency	50Hz/60Hz	Maximum output power	550/750W

## 1.2 Interface plug connections

The pedals and the machine head of the connector plug are mounted to the corresponding position in the controller back of socket, as shown in Figure 1-1. Please check if the plug is inserted firmly.



Fig.1-1 Controller Socket Diagram

① Foot lifter solenoid socket; ② Machine head solenoid socket; ③ Lifter needle lock socket; ④ Pedals socket;

 $\triangle$ : The use of the normal force are not inserted into the plug and socket, please check whether the matching, direction or needle insertion direction is correct! Lighting interface and presser foot lifting electromagnet interface is a 1\*2 interface, head lamp interface using black interface, please pay attention to the distinction.



Fig.1-2 Controller Interface Definition

## 1.3 Wiring and Grounding

We must prepare the system grounding project, please a qualified electrical engineer to be construction. Product is energized and ready for use; you must ensure that the power outlet the AC input is securely grounded. The grounding wire is yellow and green lines, it must be connected to the grid and reliable security protection on the ground to ensure safe use, and prevent abnormal situation.

⚠: All power lines, signal lines, ground lines, wiring not to be pressed into other objects or excessive distortion, to ensure safe use!

## 2 Operation Panel Instructions

## 2.1 Operation Panel Display Instruction



Fig.2-1 Operation Panel

## **Key Functions**

Key	Name	Description
R	Parameter setting key	Use the key to switch to the program mode. The key is parameters confirm key, and back to the previous menu until the operator sewing mode state. In addition, work with other key to set a higher level of the parameter.
S	Parameter modification key	Parameter to modify the confirmation key, press the <i>s</i> again to return to the standby interface.
Ĩ	Start back tacking setting key	Switch during all start tacking type when press the $H$ key is lit. (No tacking, once tacking, double tacking, 4 repeat tacking). Show $HH$ is start back tacking interface, default range 1~F corresponds to the 1~15 pin.

Key	Name	Description
Ň	End back tacking setting key	Switch during all end tacking type when press the $H$ key is lit.(No tacking, once tacking, double tacking, 4 repeat tacking). Show $HH$ is end back tacking interface, default range 1~F corresponds to the 1~15 pin.
) A	W sewing	The system enter to W sewing mode when press the ${\ensuremath{\overline{\mathbb{F}}}}$ key is lit. Show ${\ensuremath{\mathbb{Y}}} {\ensuremath{\mathbb{Y}}}$ is w sewing interface,default range 1~F corresponds to the 1~15 pin.
	Multi-section constant-stitch sewing	The system enter to multi-section constant-stitch sewing mode when press the $\textcircled{I}$ key is lit. Show $P \square \square \square$ is multi-section constant-stitch sewing interface, Use $\textcircled{I}$ key and $\square$ key to adjustment Increasing and decreasing value. Default maximum range 15.
°	Soft start setting key	Soft start at the first seam is enabled (the $\square$ key is lit ) or disabled.
البر ال	Stop position key	Select up/down stop position.Press key is lit that is called up stop position. Press key again ,the lights went out that is called down stop position.
*	Trimming cycle selection	Enable or disable the trimming cycle.the key is lit when the automatic trimming.
Ľ	Presser foot lifting Mode	Switch during all presser foot lifting mode when pressing the key is lit. (No lifting, lifting after trimming cycle only, lifting at machine stop only, lifting at machine stop and after trimming cycle both).
Ô	One-shot-sewing selection	In constant-stitch sewing: a. Press the key is lit, automatic performed number of stitches of every section. b. Press key again ,the lights went out to finish rest the sections until it finish pattern.
۴	Custom function key	Special function according to the custom requirement.
+	Up keys	Adjust the values in plus state. In addition, when the parameter is set, it can be used as the key to adjust the corresponding parameters.
Ξ	Down keys	Adjust the values minus state. In addition, when the parameter is set, it can be used as the key to adjust the corresponding parameters.

# 3 System Parameters Setting List

# 3.1 Parameter table Mode

I	NO.	Range	Default	Description

1、Long	1、Long press <sup>⊉</sup> key , the digital tube display P I⊡;				
2、Press	2. Press step to display the value of the current parameter				
	3, Press the corresponding Ekey and key to change the parameter value or selection parameter number, Press				
_	-			or selection parameter number, Press	
s key to	_				
4、At las	st press skey	to exit para	meter setting mode,return to sewing work m	ode.	
100	100~800	200	Minimum speed		
101	200~5000	3500	Maximum speed		
102	200~5000	3000	Constant-stitch sewing speed		
105	100~500	250	Trimming speed		
רסו	I~9	2	Stitch numbers for soft start		
108	100~800	200	Soft start speed		
110	200~2200	1800	Start back tacking speed		
	200~2200	1800	End back tacking speed		
115	200~2200	1800	Bar tacking speed		
ELL	I~70	24	Stitch balance for start back tacking No.1		
114	I~70	20	Stitch balance for start back tacking No.1		
115	1~70	24	Stitch balance for end back tacking No.3		
116	I I B I~70 20 Stitch balance for end back tacking No.4				
			Speed curve adjustments:		
	5/1/0 E/	ے <u>ا</u>	0: ramp curve		
130			1: polygonal curve.		
	, _		2: quadric curve		
			3: S-type curve		
131	200~4000	3000	The turning point speed of two segment cu		
132	0~ 1024	800	The turning point sampling voltage of the p	bedal when two segment curve	
			(Between parameter 138 and 139)		
133	1/2		The type of polygonal curve: 1: square	2: rooting	
134	0~ 1024	90	Trimming point of pedal		
135	0~ 1024	300	Footer lifting point of pedal		
136	0~ 1024	460	Neutral point of pedal	Figure 4-1 shows the	
רפו	0~ 1024	480	Motor running point of pedal in low speed.	specific setting method	
138	0~ 1024	580	Accelerated point of pedal		
139	0~ 1024	962	Max speed point of pedal		
I 3A	0~800	100	The running delay time of footer lifting		
			Bar tacking mode selection:		
142	0/ I	0	0: Juki mode. Active when motor stop or	running.	
			1: Brother mode. Active only when motor	running.	
			· · ·		

143	0/1/2 /3	D	Special mode: 0: normal Mode 1: simply sewing mode 2: motor initial angle measurement (Do not remove the belt) 3: Automatically setting the pulley ratio by the CPU. (synchronizer is necessary and the belt not removed)
144	D~3	0	Feedforward torque of motor: 0: normal functions 1-31: feedforward torque level
153	$I \sim 100$		The proportion coefficient of the pieces counter
154	1~9999	1	Maximum pieces of the counter
155	0~4	D	<ul> <li>Count mode selection (For Sewing Piece)</li> <li>0: The counter is invalid</li> <li>1: Count up by pieces. When count over, counter will be auto- reset.</li> <li>2: Count down by pieces. When count over, counter will be auto- reset.</li> <li>3: Count up by pieces. When count over, motor stops and the counter must be reset by the external switch or the P key on the panel.</li> <li>4: Count down by pieces. When count over, motor stops and the counter must be reset by the external switch or the P key on the panel.</li> </ul>
161	0/1/2		Direction of parameter transfer: 0: no action 1: from operation panel to controller 2: from controller to operation panel.
162	1, 2		Restore factory setting
163	1, 2		Save current parameters as user-defined default parameters.
164	-		Password
503	5-359	10	Trimming output start angle TS (down needle position angle as the reference point)
204	10-359	120	Trimming output end angle TE (Down needle position angle is the reference and this value should be bigger than TS)
20A	10-60	20	Motor torque improvement coefficient during trimming
511	5-359	25	Thread release output start angle LS (down needle position angle as the reference point)
515	10-359	350	Thread release output end angle LE (Down needle position angle is the reference and this value should be bigger than LS)
5 I S	1-999	I	Thread release output start delay time T1 (ms)
214	l~999	10	Thread release output end delay time T2 (ms) after up needle position
215	0/I		Wiper function 0: disable 1: enable
5 16	l~999	10	Wiper output delay time (ms)
רו כ	l~9999	סר	Wiper output time (ms)
2 1 9	0/I	0	Thread clamp function 0: disable 1: enable
	10-359	120	Thread clamp start angle
5 I R			
2 IA 2 IB	11-359	3 18	Thread clamp end angle
		3 18 360	Thread clamp end angle Stop position after trimming (motor can stop with a reverse angle)

234	0/1	0	Motor direction: 1: CCW 0: CW
240	0~9999	1000	The ratio between motor and machine (1000 stands for 1:1)
242	0~359	0	Up needle stop angle (After detecting the synchronizer signal)
243	0~359	175	Down needle stop angle
244	0~800	200	Running delay time when presser footer comes down (ms)
247	0~2000	0	Oil refill time alarm (hour. 0: function deactivated)
248	0~4000	٥	Oil alarm, stop operation time (hour. 0: function deactivated)
274	I~500	סר	No.2 electromagnet fully output time ms
274 275	I∼500 I∼ 100	סר ו	No.2 electromagnet fully output time ms           No.2 electromagnet chopping on time ms(Reserved)
		סר ו ו	
215	I~ 100	סר ו ו ו50	No.2 electromagnet chopping on time ms(Reserved)
215 216	I~ 100		No.2 electromagnet chopping on time ms(Reserved)         No.2 electromagnet chopping off time ms(Reserved)
215 216 218	I~ 100 I~ 100 I~500		No.2 electromagnet chopping on time ms(Reserved)         No.2 electromagnet chopping off time ms(Reserved)         No.3 electromagnet fully output time ms

1. Pressing  $\mathbb{P}_+$  ke to enter monitor mode.

2. Press and key to adjust the parameter number, press key and the para value is shown at the same time.
 3. Press key then return to normal sewing mode.

No.	Description	No.	Description
0 10	Counter for stitches	024	Machine angle
	Counter for sewing pieces	025	The sampling voltage of pedal
E I 3	State of encoder	026	The ratio between motor and machine
020	DC voltage	רכם	The total used time(hours) of motor
1 50	Machine speed	028	The sampling voltage of interaction
520	The phase current	P29	Software version
623	Initial electrical angle	030-031	The history record of error codes

# 3.3 The Warning Message

Alarm code	Description	Corrective
ALA-I	Fuel filling warning	Fuel filling. Press P key to clear.
ALA-5	Count over for stitches	The counter reaches the limit. Press P key to reset the counter.
ALA-3	Count over for sewing pieces	The counter reaches the limit. Press P key to reset the counter.
ALA-4	Emergency stop	Press the key of emergency stop to clear.
ALA-5	Lift needle locking	Then press the needle lifting locking button, can eliminate the needle lifting locking state.
Po∐oFF	Power is off	Please wait for 30 seconds, then turn on the power switch.
Arn UP	Safety switch alarm	Adjust the machine to the correct position.

## 3.4 Error Mode

If the error code appears, please check the following items first:

1.Make sure the machine has been connected correctly; 2. Reload the factory setting and try again.

Error Code	Description	Solution
Err-D I	Hardware overcurrent	Turn off the power switch, and restart after 30 seconds. If the controller still
Err-02	Software overcurrent	does not work, please replace it and inform the manufacturer.
Err-D3	Under-voltage	- Check mains voltage - Stabilize mains voltage
Err-04	Over-voltage when the machine is off	Disconnect the controller power and check if the input voltage is too high (higher than 264V). If yes, please restart the controller when the normal
Err-OS	Over-voltage in operation	voltage is resumed. If the controller still does not work when the voltage is at normal level, please replace the controller and inform the manufacturer.
Err-06	Short circuit of solenoid voltage 24V	- Take plug out, if error continues, replace control box - Test inputs/ outputs for 24V short circuit
Err-D7	Motor current measuring failure	Turn off the system power, restart after 30 seconds to see if it works well. If such failure happens frequently, seek technical support.
Err-08	Sewing motor blocked	Eliminate sluggish movement in the sewing machine     Replace encoder     Replace sewing motor
Err-09	Brake circuit failure	Check the brake resistor plug on the electric board. Replace the control box
Err-10	Communication failure	Check the connection and if necessary plug in. Replace the control box.
Err-11	Machine head needle positioning failure	Check if the connection line between machine head synchronizer and controller is loose or not, restore it and restart the system. If it still does not work, please replace the controller and inform the manufacturer.
Err- 12	Initial motor electrical angle failure	<ul> <li>-Try 2 to 3 more times after power down</li> <li>- if it still does not work, please replace the controller and inform the manufacturer.</li> </ul>
Err-13	Motor HALL failure	Turn off the system power, check if the motor sensor plug is loose or dropped off, restore it and restart the system. If it still does not work, please replace the controller and inform the manufacturer.
Err-14	DSP Read/Write EEPROM failure	
Err-15	Motor over-speed protection	Turn off the system power, restart the system after 30 seconds, if it still does
Err-16	Motor reversion	not work, please replace the controller and inform the manufacturer.
Err-17	HMI Read/Write EEPROM failure	
Err-18	Motor overload	
Err-23	Sewing motor blocked Sector error	<ul> <li>Eliminate sluggish movement in the sewing machine</li> <li>Replace encoder</li> <li>Replace sewing motor</li> </ul>

# **4 Special Functions**

## 4.1 The Adjustment of Up Needle Stop Position

1		The control system in the restoration of the factory, can be reset up needle stop position. Step 1: Press 🖅+ 🔀 key, then enter the monitor mode. Parameter 024 is
		shown, which means the default up needle stop position in angle(0 $^\circ$ ).
2	.0124	Step 2: Turn the hand wheel and adjust to the right position as up needle stop, and the needle position angle is shown simultaneously.
3	.0000	Step 3: Long press key, the new up needle position is preserved and the parameter is set to zero.Press skey to exit.
4.2	The Recovery of Defa	ult Factory Setting
1	P024	Step 1: Press 🛛 + 🐱 key, then enter the monitor mode.
2		Step 2: Press Step enter the monitor mode, long press for about 3 seconds, then Default Factory Setting is recovered displaying as left LCD.

## 4.3 Pedal Sensitivity Adjustment

Pedal starts moving from the initial position (p.136) where the motor stops, slowing forward to the low speed point (p.137) where the motor run as the minimum speed (p.100), continuing to the accelerated point (p.138) where the motor start to speed up, until the max speed point (p.139) where the motor run up to the maximum speed (p.101). And when the pedal steps back to the foot lifter position (p.135), the presser foot lift. Continuing back to the auto trimming position (p.134), the line is cut. Adjusting the corresponding parameters, user can acquire the proper pedal response to fit the personal habit.



Fig. 4-1 pedal movement of each position parameter

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